

Normalization of vectors

A unit vector is vector w/ length one

EX Show that the vector $v = \left(\frac{1}{2}, \frac{\sqrt{3}}{2}, 0\right)^T$ is a unit vector.

Compute the length $\|v\| = 1$

$$\|v\| = \left\| \left(\frac{1}{2}, \frac{\sqrt{3}}{2}, 0\right)^T \right\| = \sqrt{\left(\frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2 + 0^2} = \sqrt{\frac{1}{4} + \frac{3}{4}} = \sqrt{\frac{4}{4}} = 1$$

Normalization

We can re-scale any vector to length 1 by normalizing it, e.g. dividing the vector by its length.

$$\text{normalize}(v) = \frac{v}{\|v\|}$$

\leftarrow n -component vector

\leftarrow scalar, the length of v

EX Normalize the vector $v = (4, 3, 0)^T$

① Compute the length of v

$$\|v\| = \|(4, 3, 0)^T\| = \sqrt{16+9} = \sqrt{25} = 5$$

② Divide each component of v by $\|v\|$: $(4/5, 3/5, 0)^T$

Aside: Using GLM

← graphics library math

↳ important to use floats!

0.0f

`vec3(1.0f)` ← create vector having all components = 1

`length(v)` ← returns the length (aka magnitude) of v .

watch out! DO NOT call

`v.length()` ←

always returns 3 for a `vec3`

`cross(u, v)` ← $u \times v$

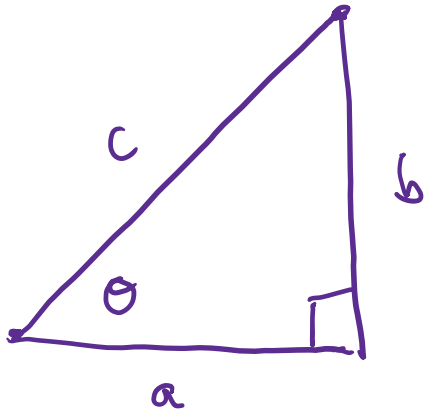
`dot(u, v)` ← $u \cdot v$

`normalize(v)`

$v - u$

$v + a$

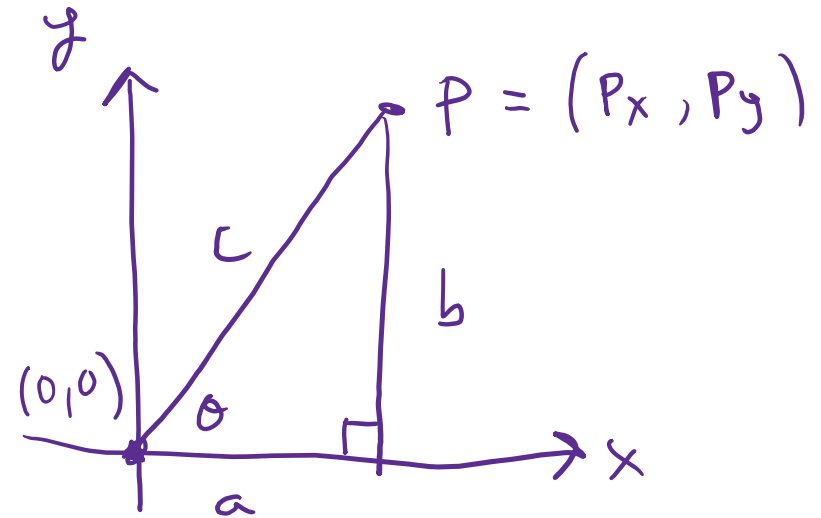
Review: Sin/Cos/Tan



$$\sin \theta = b/c$$

$$\cos \theta = a/c$$

$$\tan \theta = b/a$$



$$P_x = a = c \cos \theta$$

$$P_y = b = c \sin \theta$$

$$c = \sqrt{a^2 + b^2} = \sqrt{P_x^2 + P_y^2} = \|P\|$$

Pythagorean Rule: $a^2 + b^2 = c^2$

Moving in a circle

Let's write an algorithm in terms of `setup()` & `scene()`

```
Setup()
  theta = 0
  thetaRate = 0.1
  r = 250

Scene()
  theta += thetaRate * dt()
  float px = r * cos(theta);
  float py = r * sin(theta);
  draw Sphere (vec3(px, py, 0),
```

data

```
float theta;
float thetaRate;
float r; // distance from (0,0,0)
```

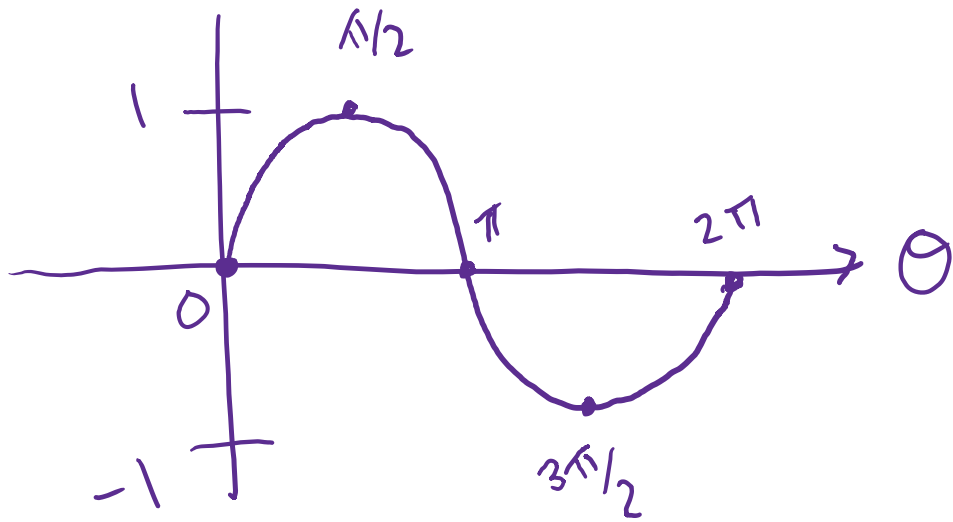
Idea: $P_x = r \cos \theta$ ← increase θ each frame:
 $P_y = r \sin \theta$
 $P_z = 0$
 $\theta = \theta + dt() * \Delta\theta$
where $\Delta\theta = \text{rate of rotation}$

formulas
rotate
around
(0,0,0)

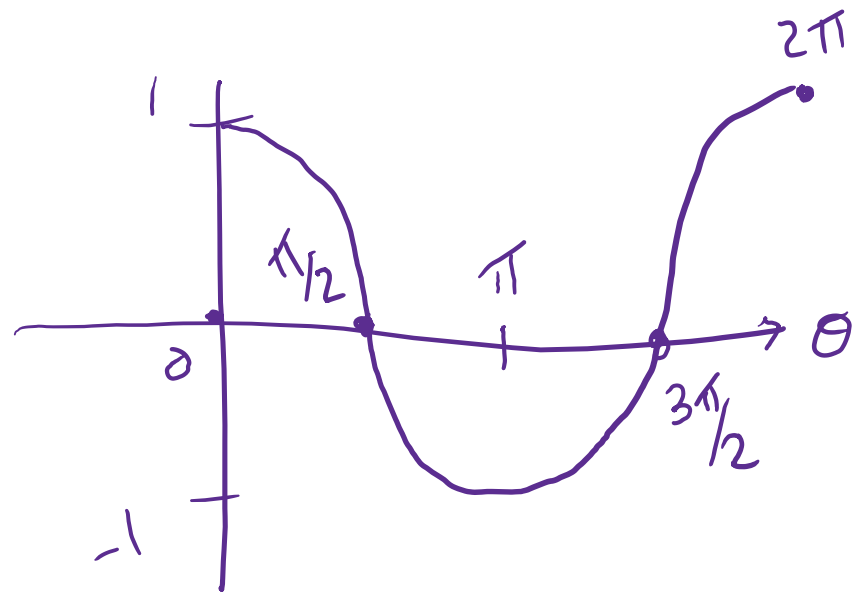
radius

Oscillating movement

Recall: the curves for sine & cosine



$\sin(\theta)$



$\cos(\theta)$

Oscillating movement

Let's animate the height of an object sine

Idea: each frame, update

Setup:
thetaRate = 0.5
theta = 0

$$y = 200 \sin(\theta)$$

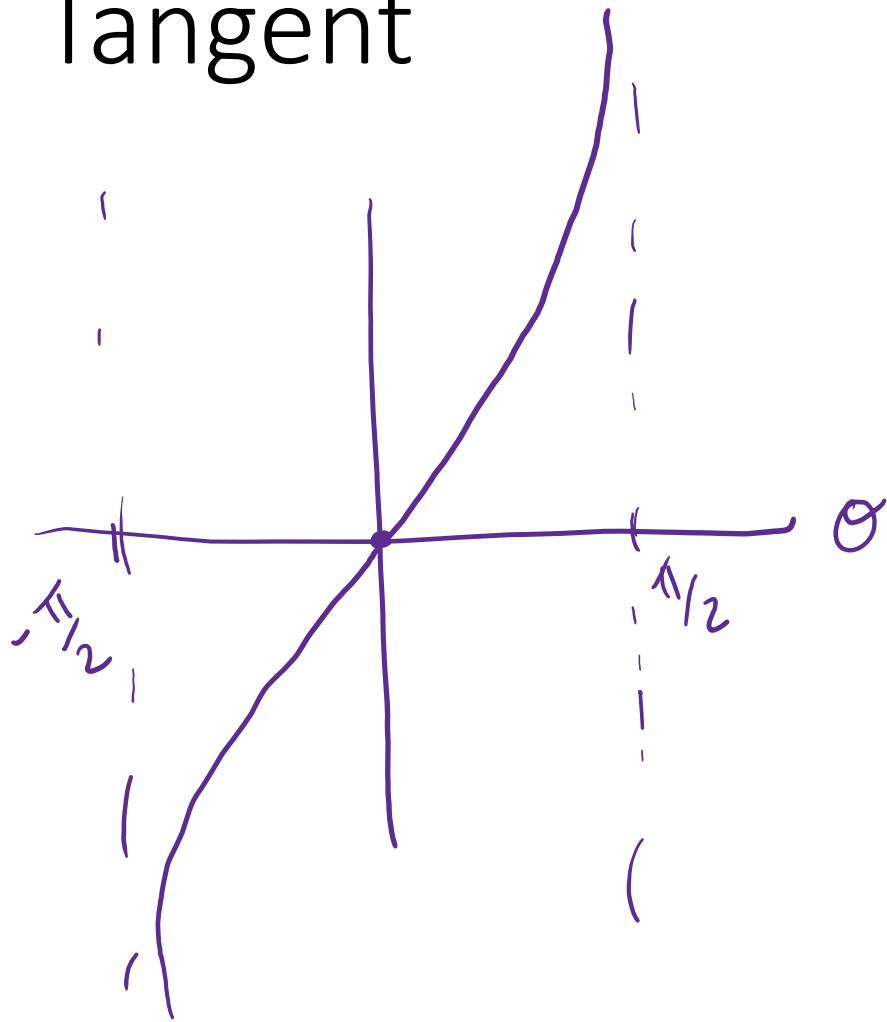
$$x = 0$$

$$z = 0$$

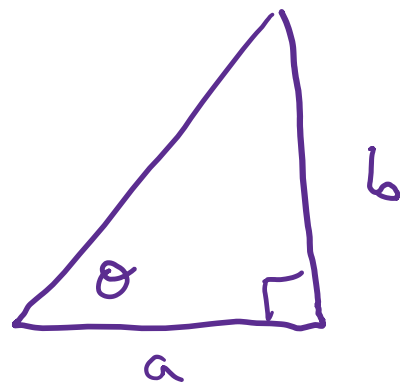
Scene:
theta += thetaRate * dt()
float py = 200 * sin(theta);
float px = 0.0
draw Sphere (vec3(px, py, 0), 100);

data [float theta
float thetaRate

Tangent



Recall: $\tan \theta = b/a$



Inverses of Sin/Cos/Tan

cos/sin take an angle $\in [-\infty, \infty]$ & outputs a value in range $[-1, 1]$

asin "arcsine" takes a value in range $[-1, 1]$ and returns an angle $\in [-\frac{\pi}{2}, \frac{\pi}{2}]$

acos "arccosine" has domain $[-1, 1]$ & returns an angle $\in [0, 2\pi]$

e.g. has domain $[-1, 1]$

watch out! these are undefined outside range $[-1, 1]$

→ NaN "not a number"

Arctangent

$\text{atan}(b/a)$

↳ outputs an angle in range $\in [-\frac{\pi}{2}, \frac{\pi}{2}]$
domain is $[-\infty, \infty]$

→
better
to
use

$\text{atan2}(b, a)$

↳ outputs angle in range $\in [0, 2\pi]$
↳ uses the signs of a & b to deduce the quadrant of the angle

